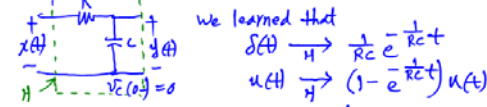


ECE103 Lecture 10, Oct 19, 2018
Application of Fourier series to system analysis

Let's consider the following RC circuit:



We learned that

$$\delta(t) \xrightarrow{H} \frac{1}{RC} e^{-\frac{t}{RC}}$$

$$u(t) \xrightarrow{H} (1 - e^{-\frac{t}{RC}}) u(t)$$

$$H(s) = \frac{Y(s)}{X(s)} = \frac{\frac{1}{sC}}{R + \frac{1}{sC}} = \frac{1}{RCs + 1}$$

$$= \left(\frac{1}{RC}\right) \frac{1}{s + \frac{1}{RC}}$$

Let $\alpha = \frac{1}{RC}$

$$H(s) = \frac{\alpha}{s + \alpha} = \frac{j\omega \tan^{-1}(\frac{\omega}{\alpha})}{\sqrt{1 + (\frac{\omega}{\alpha})^2}} = |H(j\omega)| e^{j\angle H(j\omega)}$$

For $s = j\omega$, $H(j\omega) = \frac{\alpha}{\alpha + j\omega} = \frac{1}{1 + j\omega RC} = \frac{1}{\sqrt{1 + \omega^2 RC^2}} e^{-j \tan^{-1}(\omega RC)}$

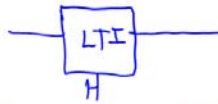
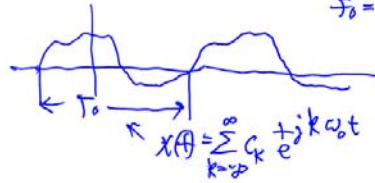
$$x(t) = \sum_{k=-\infty}^{\infty} C_k e^{+jk\omega_0 t}$$

where C_k is a complex number

$$C_k = A_k + jB_k$$

$$\omega_0 = 2\pi f_0 = \frac{2\pi}{T_0}$$

$$f_0 = \frac{1}{T_0} \text{ (period)}$$



$$x_1(t) \rightarrow y_1(t)$$

$$a x_1(t) \rightarrow a y_1(t)$$

$$x_2(t) \rightarrow y_2(t)$$

$$b x_2(t) \rightarrow b y_2(t)$$

$$a x_1(t) + b x_2(t) \rightarrow a y_1(t) + b y_2(t)$$

$$\sum_{k=1}^2 C_k e^{j\omega_k t} = C_1 e^{j\omega_1 t} + C_2 e^{j\omega_2 t} \rightarrow D_1 e^{j(\omega_1 t + \theta_1)} + D_2 e^{j(\omega_2 t + \theta_2)}$$

$$\mathcal{L}[x(t)] = X(s) \xrightarrow{H(s)} Y(s) = H(s) X(s)$$

test input $M e^{st}$

$$s = \alpha + j\omega$$

If $\alpha = 0$ $s = j\omega$

$$X(j\omega) \xrightarrow{H(j\omega)} Y(j\omega) = H(j\omega) X(j\omega)$$

$$Y(j\omega) = H(j\omega) X(j\omega)$$

$$= |H(j\omega)| e^{j\angle H(j\omega)} |X(j\omega)| e^{j\angle X(j\omega)}$$

$$= |H(j\omega)| \cdot |X(j\omega)| e^{j(\angle H(j\omega) + \angle X(j\omega))}$$

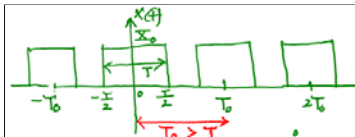
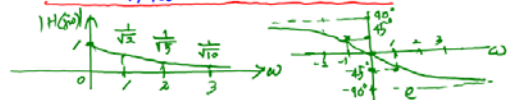
$$Y(s) = \frac{\frac{1}{sC}}{R + \frac{1}{sC}} = \frac{1}{RCs + 1}$$

$$= \frac{1}{RC} \frac{1}{s + \frac{1}{RC}}$$

$$H(s) = \frac{1}{s + \frac{1}{RC}}$$

For simplicity if $\alpha = \frac{1}{RC} = 1$, then

$$H(j\omega) = \frac{1}{1 + j\omega} = \frac{1}{\sqrt{1 + \omega^2}} e^{-j \tan^{-1}(\omega)}$$



$$x(t) = \sum_{k=-\infty}^{\infty} C_k e^{jk\omega_0 t}, \quad \omega_0 = 2\pi/T_0$$

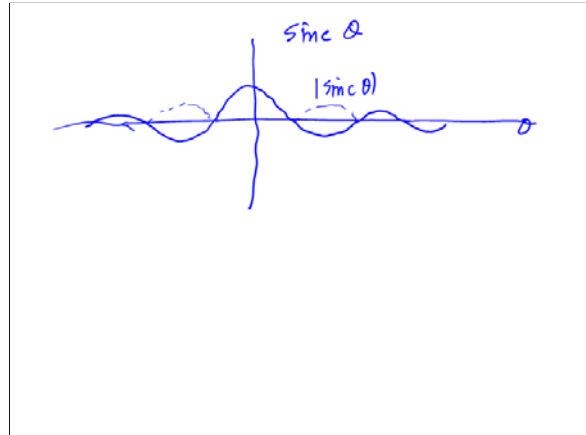
$$C_k = \frac{1}{T_0} \int_0^T x(t) e^{-jk\omega_0 t} dt$$

$$= \frac{1}{T_0} \left[\int_{-\frac{T}{2}}^0 x_0 e^{-jk\omega_0 t} dt + \int_0^{\frac{T}{2}} x_0 e^{-jk\omega_0 t} dt \right]$$

$$= \frac{x_0}{T_0} \left[\int_{-\frac{T}{2}}^0 e^{-jk\omega_0 t} dt + \int_0^{\frac{T}{2}} e^{-jk\omega_0 t} dt \right]$$

$$= \frac{x_0}{T_0} \left[\frac{1}{-jk\omega_0} (e^{-jk\omega_0 \frac{T}{2}} - 1) + \frac{1}{-jk\omega_0} (1 - e^{jk\omega_0 \frac{T}{2}}) \right]$$

$$\begin{aligned}
 C_k &= \frac{1}{T_0} \int_{-\frac{T_0}{2}}^{\frac{T_0}{2}} x_0 e^{-jk\omega_0 t} dt \\
 &= \frac{x_0}{T_0} \left[\frac{e^{-jk\omega_0 t}}{-jk\omega_0} \right]_{-\frac{T_0}{2}}^{\frac{T_0}{2}} \\
 &= \frac{x_0}{T_0} \frac{1}{-jk\omega_0} \left[e^{-jk\omega_0 \frac{T_0}{2}} - e^{-jk\omega_0 (-\frac{T_0}{2})} \right] \\
 &= \frac{x_0}{T_0} \frac{1}{-jk\omega_0} \left[e^{-jk\omega_0 \frac{T_0}{2}} - e^{jk\omega_0 \frac{T_0}{2}} \right] \\
 &= \frac{x_0}{T_0} \frac{1}{-jk\omega_0} \left[-2j \sin(k\omega_0 \frac{T_0}{2}) \right] \\
 &= \frac{x_0}{T_0} \frac{2 \sin(k\omega_0 \frac{T_0}{2})}{k\omega_0} \\
 \theta_k &= k\omega_0 \frac{T_0}{2} \quad \frac{\sin \theta_k}{\theta_k} = \frac{\sin(k\omega_0 \frac{T_0}{2})}{k\omega_0 \frac{T_0}{2}} \\
 C_k &= \frac{x_0}{T_0} \frac{\sin \theta_k}{\theta_k} = \frac{x_0}{T_0} \text{sinc } \theta_k
 \end{aligned}$$



$$\begin{aligned}
 &= \frac{x_0}{T_0} \frac{1}{-jk\omega_0} (x - e^{+jk\omega_0 \frac{T_0}{2}} + e^{-jk\omega_0 \frac{T_0}{2}} - x) \\
 &= \frac{x_0}{T_0} \frac{-1}{jk\omega_0} (e^{+jk\omega_0 \frac{T_0}{2}} - e^{-jk\omega_0 \frac{T_0}{2}}) \\
 &= \frac{x_0}{T_0} \frac{1}{k\omega_0} \frac{2j \sin(k\omega_0 \frac{T_0}{2})}{j^2} \\
 &= \frac{x_0}{T_0} \frac{2 \sin(k\omega_0 \frac{T_0}{2})}{k\omega_0} \\
 &= \frac{x_0}{T_0} \frac{T_0}{k\omega_0 \frac{T_0}{2}} \sin(k\omega_0 \frac{T_0}{2}) = \frac{x_0}{T_0} \frac{\sin \theta_k}{\theta_k} \\
 &= \frac{x_0}{T_0} \frac{\sin \theta_k}{\theta_k} = \frac{x_0}{T_0} \text{sinc } \theta_k = C_k
 \end{aligned}$$

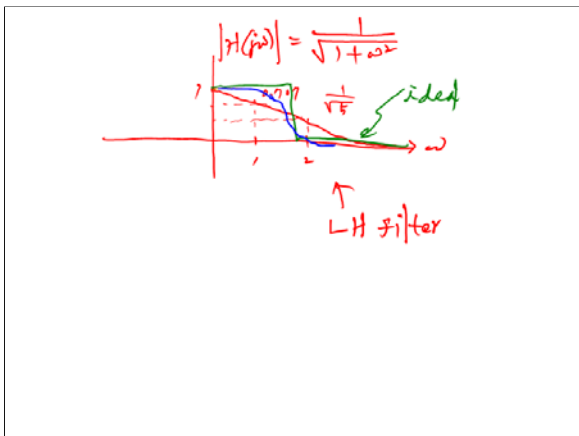
$\theta_k = k\omega_0 \frac{T_0}{2}$
 $k = \theta_k / (\omega_0 \frac{T_0}{2})$

$y(t) = \sum C_k^y e^{+jk\omega_0 t}$
 $\frac{1}{s+1}$
 $H(s) = \frac{1}{s+1}$
 $H(j\omega) = \frac{1}{1+j\omega}$
 $|H(j\omega)| = \frac{1}{\sqrt{1+\omega^2}}$
 $\angle H(j\omega) = -\tan^{-1} \omega$

$|C_k^y| = |C_k^x| |H(jk\omega_0)|$
 $\angle C_k^y = \angle C_k^x + \angle H(jk\omega_0)$

ex. what is C_5^y ?
 $C_5^y = |C_5^x| \angle C_5^y$
 $|C_5^y| = |x_0 \frac{1}{T_0} \text{sinc}(5\pi \frac{T_0}{T_0})|$
 $|H(j5\omega_0)|$
 $C_5^y = \frac{1}{\sqrt{1+(5\omega_0)^2}} \angle C_5^x + \angle H(j5\omega_0)$

$x(t) = \sum C_k^x (x_0 \frac{1}{T_0} \text{sinc } \theta_k) e^{+jk\omega_0 t}$
 $\theta_k = k\omega_0 \frac{T_0}{2} = k\pi \frac{T_0}{T_0}$
 where $\omega_0 = 2\pi/T_0$



Suppose $T_0 = 10$ $\omega_0 = 2\pi/T_0 = 0.2\pi$
 $T = 2$ $T/T_0 = 0.2$
 $x_0 = 5$

$C_k^x = x_0 \frac{1}{T_0} \text{sinc}(k\omega_0 \frac{T_0}{2}) = k\pi \frac{T_0}{T_0}$
 $C_5^x = 5(0.2) \text{sinc}(5\pi(0.2)) = 1 \text{sinc } \pi = 0$
 $C_5^y = |C_5^x| |H(j5\omega_0)| e^{j(\angle \text{sinc } \pi + \angle H(j5\omega_0))}$
 $= 0 \times \frac{1}{\sqrt{1+25}} e^{j(0 + \angle \tan^{-1} 5)} = 0 e^{j(-\tan^{-1} 5)}$

$C_6^y = |C_6^x| |H(j6\omega_0)| e^{j(\angle \text{sinc } 1.2\pi + \angle \tan^{-1} 1.2\pi)}$
 $= (\text{sinc}(1.2\pi)) \frac{1}{\sqrt{1+(1.2\pi)^2}} e^{j(180^\circ - \tan^{-1} 1.2\pi)}$

