

ECE 103 Lecture 21, November 21, 2018

**Exercise 3-2:** Determine the Laplace transform of the causal sawtooth waveform shown in Fig. E3-2 (compare with Example 1-4).

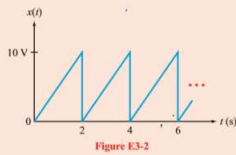


Figure E3-2

Answer:

$$X(s) = X_1(s) \sum_{n=0}^{\infty} e^{-2ns} = \frac{X_1(s)}{1 - e^{-2s}}$$

where

$$X_1(s) = \int_0^2 (5t)e^{-st} dt = \frac{5}{s^2} [1 - (2s+1)e^{-2s}]$$

3-3.4 Time Differentiation

Differentiating  $x(t)$  in the time domain is equivalent to (a) multiplying  $X(s)$  by  $s$  in the  $s$ -domain and then (b) subtracting  $x(0^+)$  from  $sX(s)$ .

$$x' = \frac{dx}{dt} \leftrightarrow sX(s) - x(0^+) \quad (3.21)$$

(time-differentiation property)

To verify Eq. (3.21), we start with the standard definition for the Laplace transform:

$$\mathcal{L}\{x'\} = \int_0^{\infty} \frac{dx}{dt} e^{-st} dt \quad (3.22)$$

Integration by parts with

$$u = e^{-st}, \quad du = -se^{-st} dt, \\ dv = \left(\frac{dx}{dt}\right) dt, \quad \text{and} \quad v = x$$

gives

$$\mathcal{L}\{x'\} = se^{-st} \Big|_0^{\infty} - \int_0^{\infty} x(-s)e^{-st} dt \\ = -e^{-s\infty} x(\infty) - \int_0^{\infty} -sx(t)e^{-st} dt \\ = -e^{-s\infty} x(\infty) + sX(s) \quad (3.23)$$

which is equivalent to Eq. (3.21). Higher derivatives can be obtained by repeating the application of Eq. (3.21). For the second derivative of  $x(t)$ , we have

$$x'' = \frac{d^2x}{dt^2} \leftrightarrow s^2 X(s) - sx(0^+) - x'(0^+) \quad (3.24)$$

(second-derivative property)

Handwritten derivation for Eq. (3.21):

$$\begin{aligned} \mathcal{L}\{x'\} &= \int_0^{\infty} \frac{dx}{dt} e^{-st} dt \\ &= x(t)e^{-st} \Big|_0^{\infty} - \int_0^{\infty} x(t)(-s)e^{-st} dt \\ &= 0 - x(0^+) - (-s) \int_0^{\infty} x(t)e^{-st} dt \\ &= -x(0^+) + sX(s) = X(s) \end{aligned}$$

3-3.5 Time Integration

Integration of  $x(t)$  in the time domain is equivalent to dividing  $X(s)$  by  $s$  in the  $s$ -domain:

$$\int_0^t x(t') dt' \leftrightarrow \frac{1}{s} X(s) \quad (3.25)$$

(time-integration property)

Application of the Laplace transform definition gives

$$\mathcal{L}\left[\int_0^t x(t') dt'\right] = \int_0^{\infty} \left[\int_0^t x(t') dt'\right] e^{-st} dt \quad (3.26)$$

Integration by parts with

$$u = \int_0^t x(t') dt', \quad du = x(t) dt, \\ dv = e^{-st} dt, \quad \text{and} \quad v = -\frac{e^{-st}}{s}$$

leads to

$$\begin{aligned} \mathcal{L}\left[\int_0^t x(t') dt'\right] &= uv \Big|_0^{\infty} - \int_0^{\infty} v du \\ &= \left[-\frac{e^{-st}}{s} \int_0^t x(t') dt'\right]_0^{\infty} + \frac{1}{s} \int_0^{\infty} x(t) e^{-st} dt = \frac{1}{s} X(s) \\ &= 0 - 0 = 0 \end{aligned} \quad (3.27)$$

Both limits on the first term on the right-hand side yield zero values.

For example, since

$$\delta(t) \leftrightarrow 1,$$

it follows that

$$u(t) = \int_0^t \delta(t') dt' \leftrightarrow \frac{1}{s}$$

and

$$r(t) = \int_0^t u(t') dt' \leftrightarrow \frac{1}{s^2}$$

Application

$$\cos \omega_0 t \xrightarrow{\mathcal{L}} \frac{s}{s^2 + \omega_0^2}$$

$$\frac{d}{dt}(\cos \omega_0 t) = -\omega_0 \sin \omega_0 t$$

$$\sin \omega_0 t = -\frac{1}{\omega_0} \frac{d}{dt}(\cos \omega_0 t)$$

$$\begin{aligned} \downarrow \mathcal{L} \quad \downarrow \mathcal{L} \\ &= -\frac{1}{\omega_0} \left[ s \left( \frac{s}{s^2 + \omega_0^2} \right) - \cos \omega_0(0) \right] \\ &= -\frac{1}{\omega_0} \left[ \frac{s^2}{s^2 + \omega_0^2} - 1 \right] \\ &= -\frac{1}{\omega_0} \frac{s^2 - (s^2 + \omega_0^2)}{s^2 + \omega_0^2} = \frac{\omega_0}{s^2 + \omega_0^2} \\ &= \mathcal{L}[\sin \omega_0 t] \end{aligned}$$

3-3.6 Initial- and Final-Value Theorems

The relationship between  $x(t)$  and  $X(s)$  is such that the initial value  $x(0^+)$  and the final value  $x(\infty)$  of  $x(t)$  can be determined directly from the expression of  $X(s)$ —provided certain conditions are satisfied (as discussed later in this subsection).

Consider the derivative property represented by Eq. (3.23) as

$$\mathcal{L}\{x'\} = \int_0^{\infty} \frac{dx}{dt} e^{-st} dt = sX(s) - x(0^+) \quad (3.28)$$

If we take the limit as  $s \rightarrow \infty$  while recognizing that  $x(0^+)$  is independent of  $s$ , we get

$$\lim_{s \rightarrow \infty} \int_0^{\infty} \frac{dx}{dt} e^{-st} dt = \lim_{s \rightarrow \infty} [sX(s)] - x(0^+) \quad (3.29)$$

The integral on the left-hand side can be split into two integrals: one over the time segment  $(0^-, 0^+)$ , for which  $e^{-st} = 1$ , and another over the segment  $(0^+, \infty)$ . Thus,

$$\lim_{s \rightarrow \infty} \int_{0^-}^{\infty} \frac{dx}{dt} e^{-st} dt = \lim_{s \rightarrow \infty} \left[ \int_{0^-}^{0^+} \frac{dx}{dt} e^{-st} dt + \int_{0^+}^{\infty} \frac{dx}{dt} e^{-st} dt \right] = x(0^+) - x(0^-) + \lim_{s \rightarrow \infty} \int_{0^+}^{\infty} \frac{dx}{dt} e^{-st} dt$$

(3.30)

As  $s \rightarrow \infty$ , the exponential function  $e^{-st}$  causes the integrand of the last term to vanish. Equating Eqs. (3.29) and (3.30) leads to

$$x(0^+) = \lim_{s \rightarrow \infty} s X(s), \quad (3.31)$$

(initial-value theorem)

which is known as the *initial-value theorem*. A similar treatment in which  $s$  is made to approach 0 (instead of  $\infty$ ) in Eq. (3.29) leads to the *final-value theorem*:

$$x(\infty) = \lim_{s \rightarrow 0} s X(s), \quad (3.32)$$

(final-value theorem)

We should note that Eq. (3.32) is useful for determining  $x(\infty)$ , so long as  $x(\infty)$  exists. Otherwise, application of Eq. (3.32) may lead to an erroneous result. Consider, for example,  $x(t) = \cos(\omega t) u(t)$ , which does not have a unique value as  $t \rightarrow \infty$ . Yet, application of Eq. (3.32) to Eq. (3.9) leads to  $x(\infty) = 0$ , which is incorrect.

e.g.)  $X(s) = \frac{1}{s^2} \xrightarrow{\mathcal{L}^{-1}} t$   
 $x(t) = u(t)$   
 $X(s) = \frac{1}{s}$   
 $-\frac{d}{ds} X(s) = -\frac{d}{ds} \left( \frac{1}{s} \right) = -\left( -\frac{1}{s^2} \right) = \frac{1}{s^2} \checkmark$

e.g.)  $r(t) = t^2 \xrightarrow{\mathcal{L}^{-1}} \frac{2}{s^3}$   
 $R(s) = \mathcal{L}\{r(t)\} = \frac{2}{s^3}$   
 $-\frac{d}{ds} R(s) = -\frac{d}{ds} \left( \frac{2}{s^3} \right) = -\left( -\frac{6}{s^4} \right) = \frac{6}{s^4} \checkmark$

Let us do direct  $\mathcal{L}$ :  
 $\mathcal{L}\{t^2\} = \int_0^{\infty} t^2 e^{-st} dt = \int_0^{\infty} t \left( \frac{e^{-st}}{s} \right) dt = \frac{1}{s} \int_0^{\infty} t e^{-st} dt = \frac{1}{s} \left( -\frac{e^{-st}}{s} \right) \Big|_0^{\infty} = \frac{1}{s^2} \checkmark$

**Example 3-5: Applying the Frequency Differentiation Property**

Given that

$$X(s) = \mathcal{L}\{e^{-at} u(t)\} = \frac{1}{s+a}$$

apply Eq. (3.35) to obtain the Laplace transform of  $te^{-at} u(t)$ .

**Solution:**

$$\mathcal{L}\{te^{-at} u(t)\} = -\frac{d}{ds} X(s) = -\frac{d}{ds} \left[ \frac{1}{s+a} \right] = \frac{1}{(s+a)^2}$$

**3-3.8 Frequency Integration**

Integrating both sides of Eq. (3.33) from  $s$  to  $\infty$  gives

$$\int_s^{\infty} X(s') ds' = \int_s^{\infty} \left[ \int_{0^-}^{\infty} x(t) e^{-s't} dt \right] ds'. \quad (3.36)$$

Since  $t$  and  $s'$  are independent variables, we can interchange the order of the integration on the right-hand side of Eq. (3.36),

$$\begin{aligned} \int_s^{\infty} X(s') ds' &= \int_{0^-}^{\infty} \left[ \int_s^{\infty} x(t) e^{-s't} ds' \right] dt \\ &= \int_{0^-}^{\infty} \left[ \frac{x(t)}{-t} e^{-s't} \Big|_s^{\infty} \right] dt \\ &= \int_{0^-}^{\infty} \left[ \frac{x(t)}{t} \right] e^{-st} dt = \mathcal{L} \left[ \frac{x(t)}{t} \right]. \end{aligned} \quad (3.37)$$

This *frequency integration property* can be expressed as

$$\frac{x(t)}{t} \leftrightarrow \int_s^{\infty} X(s') ds'. \quad (3.38)$$

(frequency integration property)

**Table 3-1: Properties of the Laplace transform for causal functions; i.e.,  $x(t) = 0$  for  $t < 0$ .**

Property	$x(t)$	$X(s) = \mathcal{L}\{x(t)\}$
1. Multiplication by constant	$K x(t)$	$\leftrightarrow K X(s)$
2. Linearity	$K_1 x_1(t) + K_2 x_2(t)$	$\leftrightarrow K_1 X_1(s) + K_2 X_2(s)$
3. Time scaling	$x(at), a > 0$	$\leftrightarrow \frac{1}{a} X\left(\frac{s}{a}\right)$
4. Time shift	$x(t - T) u(t - T)$	$\leftrightarrow e^{-Ts} X(s)$
5. Frequency shift	$e^{-at} x(t)$	$\leftrightarrow X(s + a)$
6. Time 1st derivative	$x' = \frac{dx}{dt}$	$\leftrightarrow sX(s) - x(0^-)$
7. Time 2nd derivative	$x'' = \frac{d^2x}{dt^2}$	$\leftrightarrow s^2X(s) - sx(0^-) - x'(0^-)$
8. Time integral	$\int_0^t x(t') dt'$	$\leftrightarrow \frac{1}{s} X(s)$
9. Frequency derivative	$t x(t)$	$\leftrightarrow -\frac{d}{ds} X(s) = -X'(s)$
10. Frequency integral	$\frac{x(t)}{t}$	$\leftrightarrow \int_s^{\infty} X(s') ds'$
11. Initial value	$x(0^+)$	$= \lim_{s \rightarrow \infty} s X(s)$
12. Final value	$\lim_{t \rightarrow \infty} x(t) = x(\infty)$	$= \lim_{s \rightarrow 0} s X(s)$
13. Convolution	$x_1(t) * x_2(t)$	$\leftrightarrow X_1(s) X_2(s)$

**Exercise 3-7: Obtain the Laplace transform of**

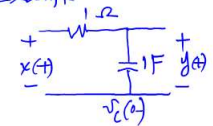
- (a)  $x_1(t) = 2(2 - e^{-t}) u(t)$  and
- (b)  $x_2(t) = e^{-3t} \cos(2t + 30^\circ) u(t)$ .

**Answer:** (a)  $X_1(s) = \frac{2s + 4}{s(s + 1)}$ ,  
 (b)  $X_2(s) = \frac{0.866s + 1.6}{s^2 + 6s + 13}$ . (See  $\textcircled{S}$ )

$$\cos(2t + 30^\circ) = \cos 2t \underbrace{\cos 30^\circ}_{=0.866} - \sin 2t \underbrace{\sin 30^\circ}_{=0.5}$$

$$\begin{aligned} e^{-3t} \cos 3t &\xrightarrow{\mathcal{L}} \frac{(s+3)}{(s+3)^2 + 3^2} \\ e^{-3t} (\cos 3t \cdot 0.866 - \sin 3t \cdot 0.5) \\ &= \frac{0.866(s+3)}{(s+3)^2 + 3^2} - \frac{3 \times 0.5}{(s+3)^2 + 3^2} \\ &= \frac{0.866s + 3(0.866) - 1.5}{s^2 + 6s + 18} \end{aligned}$$

Example

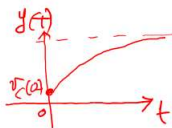


$$\begin{aligned} x(t) &= 1 \left( 1 \frac{dy(t)}{dt} \right) + y(t) \\ x(s) &= (sY(s) - y(0^-)) + Y(s) \\ Y(s) &= \frac{x(s) + v_c(0^-)}{s+1} \\ y(0^-) &= v_c(0^-) \end{aligned}$$

For  $x(t) = u(t)$ ,  $x(s) = \frac{1}{s}$ ,  $Y(s) = \frac{\frac{1}{s} + v_c(0^-)}{s+1}$

$$= \frac{1}{s(s+1)} + \frac{v_c(0^-)}{s+1}$$

$$= \frac{1}{s} - \frac{1}{s+1}$$

$$y(t) = (1 - e^{-t})u(t) + v_c(0^-)e^{-t}u(t)$$


For  $x(t) = 1 \sin 10t u(t)$

$$\begin{aligned} x(s) &= \frac{10}{s^2 + 10^2} \\ Y(s) &= \frac{\frac{10}{s^2 + 10^2} + v_c(0^-)}{s+1} \\ &= \left( \frac{10}{s^2 + 10^2} \right) \frac{1}{s+1} + \frac{v_c(0^-)}{s+1} \end{aligned}$$

where

$$\frac{10}{(s^2 + 10^2)(s+1)} = \frac{A}{s+j10} + \frac{B=A^*}{s-j10} + \frac{C}{s+1}$$

$$C = \left. \frac{10}{(s^2 + 10^2)(s+1)} \right|_{s=-1} = \frac{10}{101}$$

$$A = \left. \frac{10}{(s^2 + 10^2)(s+1)} \right|_{s=j10} = \frac{10}{(s-j10)(s+1)} \Big|_{s=j10}$$

$$\begin{aligned} &= \frac{10}{-j20(1-j10)} = \frac{+j}{2(1-j10)} \\ A^* &= \frac{-j}{2(1+j10)} \\ \Rightarrow Y(s) &= \frac{+j}{2(1-j10)} + \frac{-j}{2(1+j10)} + \frac{10}{s+1} + \frac{v_c(0^-)}{s+1} \\ &= \frac{+j}{2(1-j10)} \frac{(s-j10) - j(1+j10)}{(s+j10)(s-j10)} + \frac{10}{s+1} + \frac{v_c(0^-)}{s+1} \\ &= \frac{j(s-j10)(1+j10) - j(s+j10)(1-j10)}{2(1-j10)(1+j10)} + \left( \frac{10}{s+1} \right) + \frac{v_c(0^-)}{s+1} \\ &= \frac{1}{s^2 + 10^2} j(s+j10s-j10 - (100) - (2-j10s+j10 - (100))) \left( \frac{10}{s+1} \right) \\ &= \frac{1}{s^2 + 10^2} j(s+j10s-j10 - (100) - (2-j10s+j10 - (100))) \left( \frac{10}{s+1} \right) \end{aligned}$$

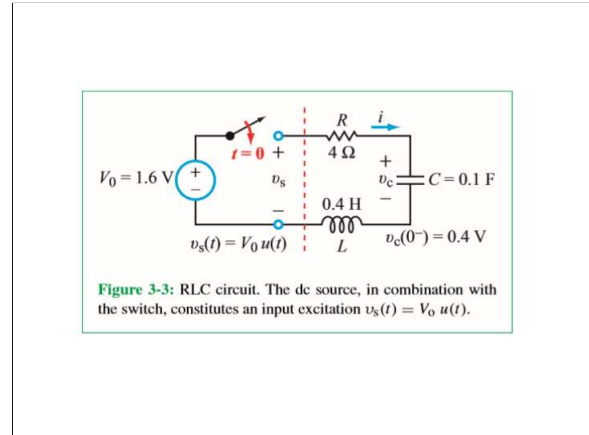
$$\begin{aligned} + \frac{v_c(0^-)}{s+1} &= \frac{1}{2(101)} j(j20s - j20) + \frac{10}{s+1} + \frac{v_c(0^-)}{s+1} \\ &= \frac{10}{101} \frac{(1-j)}{s^2 + 10^2} + \frac{10}{s+1} + \frac{v_c(0^-)}{s+1} \\ &\downarrow e^{-t} \\ y(t) &= u(t) \left[ \frac{1}{101} \sin 10t - \frac{10}{101} \cos 10t + \left( \frac{v_c(0^-) + \frac{10}{101}}{s+1} \right) e^{-t} \right] \\ &= u(t) \left[ \frac{1}{\sqrt{101}} \sin(10t - \tan^{-1} 10) + \left( \frac{v_c(0^-) + \frac{10}{101}}{s+1} \right) e^{-t} \right] \end{aligned}$$

In steady state ( $s \rightarrow \infty$ )

$$y_{SS}(t) = \frac{1}{\sqrt{101}} \sin(10t - 84.29^\circ)$$

transient

Handwritten notes for the Laplace transform of an RLC circuit. It shows the transfer function  $H(\omega) = \frac{Y(\omega)}{X(\omega)} = \frac{Yj\omega C}{1 + Yj\omega C} = \frac{1}{j\omega C + 1}$ . For  $X(t) = 1 \sin \omega t = 1 \sin 10t$ , with  $\omega = 10$ , the transfer function is  $H(\omega=10) = \frac{1}{1 + j10} = \frac{1}{\sqrt{1+10^2}} e^{j \angle \tan^{-1}(10)}$ . This simplifies to  $\frac{1}{\sqrt{101}} e^{j(-84.29^\circ)}$ . The final output is  $\Rightarrow \underline{y_{ss}(t)} = \frac{1}{\sqrt{101}} \sin(10t - 84.29^\circ)$ , which is marked as "matches".



Equation (3.46):  $R i(t) + \left[ \frac{1}{C} \int_0^t i(t') dt' + v_c(0^-) \right] + L \frac{di(t)}{dt} = V_0 u(t)$

**Step 2:** Define  $I(s)$  as the Laplace transform corresponding to the unknown current  $i(t)$ , obtain s-domain equivalents for each term in Eq. (3.46), and then apply the linearity property of the Laplace transform to transform the entire integrodifferential equation into the s-domain.

The four terms of Eq. (3.46) have the following Laplace transform pairs:

- $R i(t) \leftrightarrow R I(s)$
- $\frac{1}{C} \int_0^t i(t') dt' + v_c(0^-) \leftrightarrow \frac{1}{C} \left[ \frac{I(s)}{s} \right] + \frac{v_c(0^-)}{s}$  (time integral property)
- $L \frac{di(t)}{dt} \leftrightarrow L[s I(s) - i(0^-)]$  (time derivative property)

and

$V_0 u(t) \leftrightarrow \frac{V_0}{s}$

Equation (3.47):  $R I(s) + \frac{I(s)}{Cs} + \frac{v_c(0^-)}{s} + Ls I(s) = \frac{V_0}{s}$

where we have set  $i(0^-) = 0$ , because no current could have been flowing through the loop prior to closing the switch. Equation (3.47) is the s-domain equivalent of the integrodifferential equation (3.46). Whereas Eq. (3.46) has time-derivatives and integrals, Eq. (3.47) is a simple algebraic equation in  $s$ .

The beauty of the Laplace transform is that it converts an integrodifferential equation in the time domain into a straightforward algebraic equation in the s-domain.

Solving for  $I(s)$  and then replacing  $R, L, C, V_0$ , and  $v_c(0^-)$  with their numerical values leads to

$$I(s) = \frac{V_0 - v_c(0^-)}{L \left[ s^2 + \frac{R}{L}s + \frac{1}{LC} \right]} = \frac{1.6 - 0.4}{0.4 \left( s^2 + \frac{4}{0.4}s + \frac{1}{0.4 \times 0.1} \right)}$$

$$= \frac{3}{s^2 + 10s + 25} = \frac{3}{(s+5)^2} \quad (3.48)$$

According to entry #6 in Table 3-2, we have

$$\mathcal{L}^{-1} \left[ \frac{1}{(s+a)^2} \right] = t e^{-at} u(t)$$

Hence,

$$i(t) = 3t e^{-5t} u(t) \quad (3.49)$$

Find  $v_c(t)$

**Figure 3-3:** RLC circuit. The dc source, in combination with the switch, constitutes an input excitation  $v_s(t) = V_0 u(t)$ .

Handwritten equation:  $v_s(t) = R \left( C \frac{dv_c(t)}{dt} \right) + v_c(t) + L \frac{d}{dt} \left( C \frac{dv_c(t)}{dt} \right)$

Handwritten derivation for  $v_c(t)$ :

$$v_s(t) = R \left( C \frac{dv_c(t)}{dt} \right) + v_c(t) + L \frac{d}{dt} \left( C \frac{dv_c(t)}{dt} \right)$$

$$= RC \frac{dv_c(t)}{dt} + v_c(t) + LC \frac{d^2 v_c(t)}{dt^2}$$

↓  $\mathcal{L}$

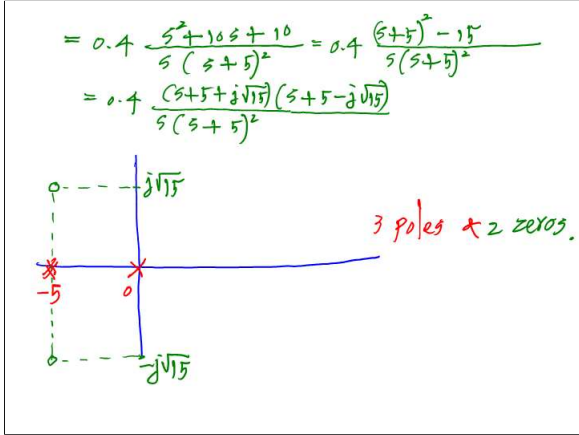
$$V_s(s) = RC(sV_c(s) - v_c(0^-)) + V_c(s) + LC(s^2 V_c(s) - s v_c(0^-) - v_c'(0^-))$$

$$= 0.4(sV_c(s) - 0.4) + V_c(s) + 0.04(s^2 V_c(s) - s \cdot 0.4 - 0)$$

$$= 0.04s^2 V_c(s) + 0.4s V_c(s) + V_c(s) - 0.16 - 0.016s = \frac{1.6}{s}$$

$$V_c(s) = \frac{1.6}{s} + 0.016s + 0.16 \cdot \frac{1}{0.04s^2 + 0.4s + 1}$$

$$= \frac{0.16}{0.04} \frac{1}{s^2 + 10s + 25} = 4 \frac{1}{(s+5)^2}$$



### 3-5 Partial Fraction Expansion

Let us assume that, after transforming the integrodifferential equation associated with a system of interest to the s-domain and then solving it for the output signal whose behavior we wish to examine, we end up with an expression like  $X(s)$ . Our next step is to inverse transform  $X(s)$  to the time domain, thereby completing our solution. The degree of mathematical difficulty associated with the implementation of the inverse transformation depends on the mathematical form of  $X(s)$ . Consider for example the expression

$$X(s) = \frac{4}{s+2} + \frac{6}{s+5j} + \frac{4}{s^2+4s+5} \quad (3.50)$$

The inverse transform,  $x(t)$ , is given by

$$x(t) = \mathcal{L}^{-1}\{X(s)\} = \mathcal{L}^{-1}\left[\frac{4}{s+2}\right] + \mathcal{L}^{-1}\left[\frac{6}{s+5j}\right] + \mathcal{L}^{-1}\left[\frac{4}{s^2+4s+5}\right] \quad (3.51)$$

By comparison with the entries in Table 3-2, we note the following:

- (a) The first term in Eq. (3.51),  $4/(s+2)$ , is functionally the same as entry #1 in Table 3-2 with  $a = -2$ . Hence,
 
$$\mathcal{L}^{-1}\left[\frac{4}{s+2}\right] = 4e^{-2t}u(t) \quad (3.52a)$$
- (b) The second term,  $6/(s+5j)$ , is functionally the same as entry #6 in Table 3-2 with  $a = -5$ . Hence,
 
$$\mathcal{L}^{-1}\left[\frac{6}{s+5j}\right] = 6e^{-5t}u(t) \quad (3.52b)$$
- (c) The third term  $4/(s^2+4s+5)$  is similar (but not identical) in form to entry #13 in Table 3-2. However, it can be rearranged to assume the proper form:
 
$$\frac{4}{s^2+4s+5} = \frac{4}{(s+2)^2+1}$$
 Consequently,
 
$$\mathcal{L}^{-1}\left[\frac{4}{(s+2)^2+1}\right] = 4e^{-2t}\sin t u(t) \quad (3.52c)$$

For  $H(s) = \frac{0.4(s^2+5s+10)}{s(s+5)^2}$   
 Let's find its partial fraction expansion

$$H(s) = \frac{A}{s} + \frac{Bs+C}{(s+5)^2}$$

$$A = H(s) \cdot s \Big|_{s=0} = \frac{0.4(s^2+5s+10)}{s(s+5)^2} \Big|_{s=0} = \frac{0.4(0+0+10)}{(0+5)^2} = \frac{4}{25}$$

$$\frac{As+B}{(s+5)^2} = H(s) - \frac{4}{25s} = \frac{0.4s^2+2s+4}{s(s+5)^2} - \frac{4}{25s} \frac{(s+5)^2}{(s+5)^2}$$

$$\frac{As+B}{(s+5)^2} = \frac{0.4s^2+2s+4 - (0.16s^2+1.6s+4)}{s(s+5)^2}$$

$$= \frac{0.24s^2+3.6s}{s(s+5)^2} = \frac{0.24s+3.6}{(s+5)^2}$$

$\Rightarrow A = 0.24, B = 3.6$

Finally  $H(s) = \frac{0.24}{s} + \frac{0.24s}{(s+5)^2} + \frac{0.36}{(s+5)^2}$

$u(t) \leftrightarrow \frac{1}{s}$   
 $e^{-at}u(t) \leftrightarrow \frac{1}{s+a}$   
 $-t e^{-at}u(t) \leftrightarrow \frac{1}{(s+a)^2}$   
 $+t e^{-at}u(t) \leftrightarrow \frac{1}{(s+a)^2}$

$$\frac{d}{dt}(t e^{-at}u(t)) \leftrightarrow \frac{s}{(s+a)^2} \quad \frac{dx}{dt} \leftrightarrow sX(s) - x(0)$$

$$= e^{-at}u(t) - at e^{-at}u(t) + t e^{-at} \delta(t)$$

$$= e^{-at}u(t) - at e^{-at}u(t) + 0$$

$\downarrow \mathcal{L}$

$$\frac{1}{s+a} - a \frac{1}{(s+a)^2} = \frac{s+a-a}{(s+a)^2} = \frac{s}{(s+a)^2}$$