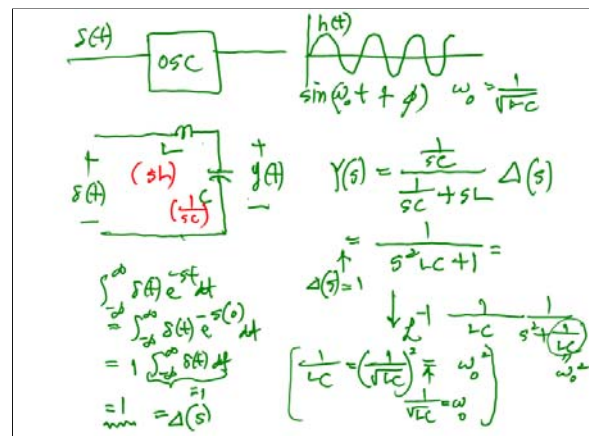
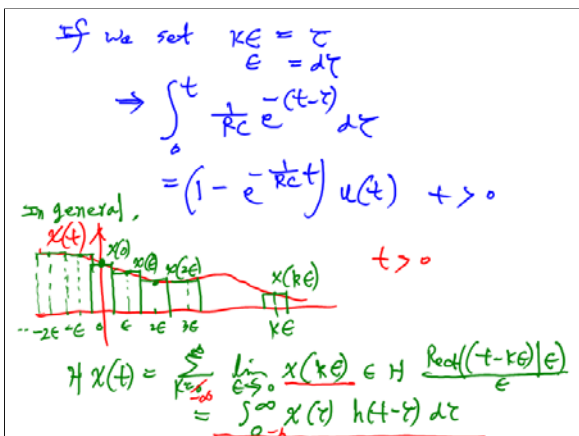
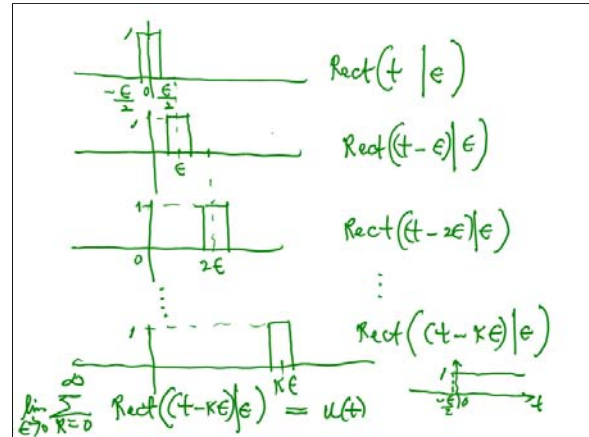
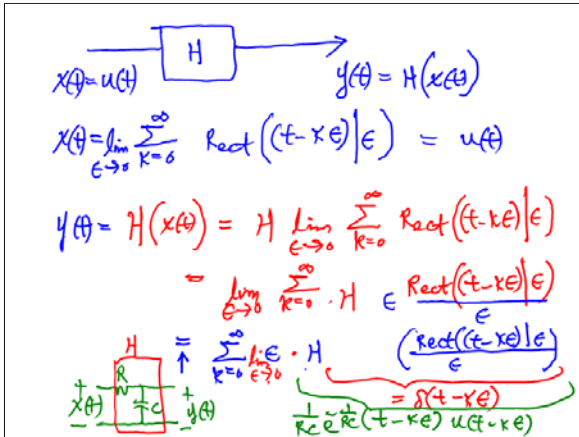
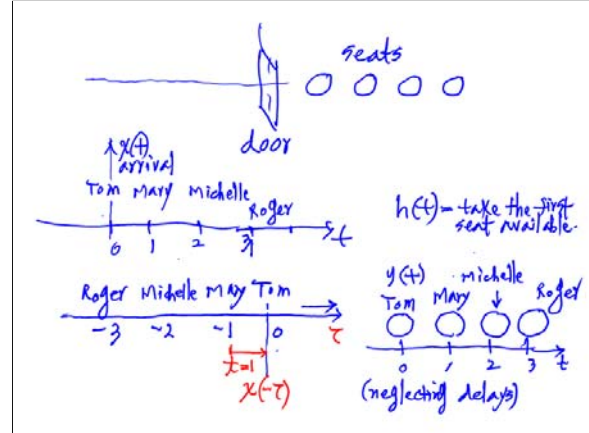
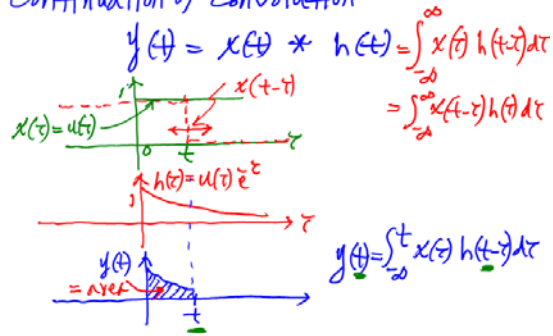


ECE 103 Lecture #6 Oct 10, 2018  
 Continuation of convolution



$$Y(s) = \frac{1}{LC} \frac{1}{s^2 + \omega_0^2} = \frac{1}{LC} \frac{1}{(s + j\omega_0)(s - j\omega_0)}$$

$$= \frac{1}{LC} \left( \frac{A}{s + j\omega_0} + \frac{B}{s - j\omega_0} \right)$$

$$A = \dots \frac{1}{2j\omega_0}$$

$$B = \dots \frac{1}{-2j\omega_0}$$

$y(t) = \text{sinusoidal function}$

$x(t) \xrightarrow{\text{LTI}} y(t)$   $y(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau) d\tau = x(t) * h(t)$  (3.14)

$y(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau) d\tau = \int_{-\infty}^{\infty} x(t-s)h(s) [-ds]$

$$= \int_{-\infty}^{\infty} x(t-s)h(s) ds = \int_{-\infty}^{\infty} x(t-\tau)h(\tau) d\tau$$

Next we derive an important property of the convolution integral by making a change of variables in (3.13); let  $s = (t - \tau)$ . Then  $\tau = (t - s)$  and  $d\tau = -ds$ . Equation (3.13) becomes

$$y(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau) d\tau = \int_{-\infty}^{\infty} x(t-s)h(s) [-ds]$$

$$= \int_{-\infty}^{\infty} x(t-s)h(s) ds = \int_{-\infty}^{\infty} x(t-\tau)h(\tau) d\tau$$

Next we replace  $s$  with  $\tau$  in the last integral, and thus the convolution can also be expressed as

$$y(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau) d\tau = \int_{-\infty}^{\infty} x(t-\tau)h(\tau) d\tau. \quad (3.15)$$

The convolution integral is symmetrical with respect to the input signal  $x(t)$  and the impulse response  $h(t)$ , and we have the property

$$y(t) = x(t) * h(t) = h(t) * x(t) \quad (3.16)$$

commutative

**Prob. (5th Ed) 3.8 (d)**

$x(t) = e^{-t}u(t)$ ,  $h(t) = u(t-1) - u(t-3)$

Find  $y(t) = x(t) * h(t)$

Solution:   
 $y(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau) d\tau$

For  $t \leq 1$ ,  $y(t) = 0$   
 For  $1 < t < 2$ ,  $y(t) = \int_0^t e^{-\tau} d\tau = 1 - e^{-t}$   
 For  $2 < t < 3$ ,  $y(t) = \int_0^t e^{-\tau} d\tau = 1 - e^{-t}$   
 For  $t \geq 3$ ,  $y(t) = 0$

For  $t=3$ ,  $y(3) = \int_0^2 e^{-\tau} d\tau = -e^{-\tau} \Big|_0^2 = 1 - e^{-2} = 0.86$

For  $t=4$ ,  $y(4) = \int_1^3 e^{-\tau} d\tau = -e^{-\tau} \Big|_1^3 = e^{-1} - e^{-3} = 0.37 - 0.05 = 0.32$

Alternatively  $y(t) = x(t) * h(t) = h(t) * x(t) = \int_{-\infty}^{\infty} h(\tau)x(t-\tau) d\tau$

$y(t) = 0$  for  $t \leq 1$   
 For  $1 < t < 2$ ,  $y(t) = \int_1^{t-1} e^{-(t-\tau)} d\tau = e^{-t} [e^{\tau}]_1^{t-1} = 1 - e^{-1} = 0.63$

$y(3) = \int_1^2 e^{-(3-\tau)} d\tau = e^{-3} [e^{\tau}]_1^2 = e^{-3} (e^2 - e) = 1 - e^{-1} = 0.86$

$y(4) = \int_1^3 e^{-(4-\tau)} d\tau = e^{-4} [e^{\tau}]_1^3 = e^{-4} (e^3 - e) = 0.37 - 0.05 = 0.32$

**Properties of Convolution**

- Commutative:  $x(t) * h(t) = h(t) * x(t)$
- Associative:  $x(t) * (h_1(t) * h_2(t)) = (x(t) * h_1(t)) * h_2(t)$

3. Distributive

$$x(t) * [h_1(t) + h_2(t)] = x(t) * h_1(t) + x(t) * h_2(t)$$

Bounded Input Bounded Output (BIBO) stability

Bounded in amplitude i.e.  $|x(t)| < M_i$  → BIBO stable system → Bounded in amplitude  $|y(t)| < M_o$

$$y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau = \int_{-\infty}^{\infty} x(t-\tau) h(\tau) d\tau$$

Taking absolute value (absolute value on both sides)

$$|y(t)| = \left| \int_{-\infty}^{\infty} x(t-\tau) h(\tau) d\tau \right| \leq \int_{-\infty}^{\infty} |x(t-\tau)| |h(\tau)| d\tau < M_i \int_{-\infty}^{\infty} |h(\tau)| d\tau \Rightarrow \text{bounded } y(t) \text{ is bounded}$$

$x(t) \rightarrow h(t) \rightarrow y(t)$  is BIBO stable  
 $\Rightarrow \int_{-\infty}^{\infty} |h(\tau)| d\tau < \infty$   
 sufficient condition for BIBO stability.

When system is causal For  $x(t)$  apply for  $t \geq 0, y(t) = 0$  for  $t < 0$

and  $\int_{-\infty}^{\infty} |h(\tau)| d\tau = \int_0^{\infty} |h(\tau)| d\tau < \infty$   
 becomes the sufficient condition for BIBO stability

(Eg.) If  $h(t) = u(t)$  (Integrator)

then  $\int_0^{\infty} |h(\tau)| d\tau = \int_0^{\infty} 1 d\tau = \infty$   
 not BIBO stable.

In fact when  $x(t) = u(t)$ ,  
 $y(t) = \int_0^t x(\tau) h(t-\tau) d\tau = \int_0^t u(\tau) d\tau = t$

$y(t) \rightarrow \infty$  as  $t \rightarrow \infty$   
 $|y(t)| \not< \infty$  for all  $t$   
 (not BIBO stable)

(Eg.)  $H(s) = \frac{1}{RCs+1}$

we learned that for  $x(t) = u(t), y(t) = 1 - e^{-\frac{t}{RC}}$

By linearity when  $x(t) = M u(t), y(t) = M(1 - e^{-\frac{t}{RC}})$

$|x(t)| \leq M$  for all  $t, |y(t)| \leq M$  for all  $t$

BIBO stable  
 (Because R dissipated energy !)